



#### Modèles et méthodes pour l'acquisition des images couleurs matricées

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A (Bayer) color filter array (CFA) is overlaid on the sensor





what you see

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#### Color image acquisition with a single sensor



A (Bayer) color filter array (CFA) is overlaid on the sensor





### Outline

- The challenge of demosaicking
  - An image formation model
  - «Denoisaicking» methods
  - New robust CFAs

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### Luminance / chrominance basis

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# Frequency interpretation of Bayer sampling

[Alleysson *et al., IEEE TIP*, 2005]



Fourier transform



$$\hat{v}(\boldsymbol{\omega}) = \frac{1}{\sqrt{3}}\hat{u}^{L}(\boldsymbol{\omega}) + \frac{1}{\sqrt{24}}\hat{u}^{G/M}(\boldsymbol{\omega}) + \frac{\sqrt{6}}{4}\hat{u}^{G/M}(\boldsymbol{\omega} - [\pi, \pi]^{\mathrm{T}}) + \frac{\sqrt{2}}{4}\hat{u}^{R/B}(\boldsymbol{\omega} - [0, \pi]^{\mathrm{T}}) - \frac{\sqrt{2}}{4}\hat{u}^{R/B}(\boldsymbol{\omega} - [\pi, 0]^{\mathrm{T}})$$

# Frequency interpretation of Bayer sampling

[Alleysson *et al., IEEE TIP*, 2005]



Fourier transform



$$\begin{aligned} v[\mathbf{k}] &= \frac{1}{\sqrt{3}} u^{L}[\mathbf{k}] + \frac{1}{\sqrt{24}} u^{G/M}[\mathbf{k}] + \frac{\sqrt{6}}{4} (-1)^{k_{1}+k_{2}} u^{G/M}[\mathbf{k}] + \\ & \frac{\sqrt{2}}{4} (-1)^{k_{2}} u^{R/B}[\mathbf{k}] - \frac{\sqrt{2}}{4} (-1)^{k_{1}} u^{R/B}[\mathbf{k}] \end{aligned}$$

# Linear demosaicking by frequency selection

Chrominance obtained by modulation + lowpass filtering 

$$d^{G/M} = \frac{4}{\sqrt{6}} v_{\pi,\pi} * h_{G/M} \text{ where } v_{\pi,\pi}[\mathbf{k}] = (-1)^{k_1 + k_2} v[\mathbf{k}]$$
  

$$d^{R/B}_H = -2\sqrt{2} v_{\pi,0} * h_{R/B} \text{ where } v_{\pi,0}[\mathbf{k}] = (-1)^{k_1} v[\mathbf{k}]$$
  

$$d^{R/B}_V = 2\sqrt{2} v_{0,\pi} * (h_{R/B})^{\mathrm{T}} \text{ where } v_{0,\pi}[\mathbf{k}] = (-1)^{k_2} v[\mathbf{k}]$$
  

$$d^{R/B} = \frac{1}{2} (d^{R/B}_H + d^{R/B}_V)$$



Luminance as the residual 

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$$\frac{1}{\sqrt{3}}d^L = v[\mathbf{k}] - \left(\frac{1}{\sqrt{24}} + \frac{\sqrt{6}}{4}(-1)^{k_1 + k_2}\right)d^{G/M}[\mathbf{k}] - \frac{\sqrt{2}}{4}\left((-1)^{k_2} - (-1)^{k_1}\right)d^{R/B}[\mathbf{k}]$$

#### [Dubois, *IEEE SPL*, 2005]

#### Result

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• Aliasing artifacts due to highfrequency content of luminance







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#### Adaptive demosaicking based on the structure tensor

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- The challenge of demosaicking
- An image formation model

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- «Denoisaicking» methods
- New robust CFAs





in Digital Cameras, Süsstrunk]



# Simplified acquisition model

• We ignore:

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- the spectral sensitivity functions of the R,G,B filters
- cross-talk
- non-linearities of the sensor, A/D conversion
- white balancing
- optical blur due to the optical system

# Simplified acquisition model

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$$\begin{aligned} \mathbf{v}[\mathbf{k}] &= \mathcal{C} \left( \mathcal{G}^{-1}(\mathrm{im}^X[\mathbf{k}]) + \sqrt{a \, \mathcal{G}^{-1}(\mathrm{im}^X[\mathbf{k}]) + b \, e[\mathbf{k}]} \right) \\ & \swarrow \\ & \mathsf{clipping} \\ & \mathsf{inverse of tone mapping} \\ & \mathcal{G}(x)^{-1} \approx x^{2.2} \end{aligned}$$

### **Reconstruction procedure**

$$v[\mathbf{k}] = \mathcal{C}\left(\mathcal{G}^{-1}(\mathrm{im}^X[\mathbf{k}]) + \sqrt{a\,\mathcal{G}^{-1}(\mathrm{im}^X[\mathbf{k}]) + b\,e[\mathbf{k}]}\right)$$

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 variance stabilization (clipping taken into account)
 joint demosaicking/denoising in the AWGN setting
 pixel-wise mapping: bias correction E{f(x)} ≠ f(E{x}) + inverse stabilization + unclipping + tone mapping

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# Naive approaches to joint demosaicking/denoising



#### Original image



#### Demosaicked image



Demosaicking + denoising



Denoising + demosaicking



Joint demosaicking/ denoising [Hirakawa, 2006]

### Ad hoc approaches

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Hirakawa et al. "Joint demosaicing and denoising", IEEE TIP, 2006



# Linear demosaicking: behavior under noise

 $v[\mathbf{k}] = v_0[\mathbf{k}] + \varepsilon[\mathbf{k}]$   $\varepsilon[\mathbf{k}] \sim \mathcal{N}(0, \sigma^2)$ 

• Let  $d_0$  be the demosaicked image in absence of noise

 $\mathbf{d}[\mathbf{k}] = \mathbf{d}_0[\mathbf{k}] + \mathbf{e}[\mathbf{k}]$ 



- The demosaicked color noise e is such that:
  - $e^{G/M}$ ,  $e^{R/B}$ ,  $e^{L}$  are independent Gaussian noise realizations
  - $e^{G/M}$  is stationary with spectral density  $\frac{8}{3}\sigma^2|\hat{h}_{G/M}(\boldsymbol{\omega})|^2$
  - $e^{R/B}$  is stationary with spect. dens.  $2\sigma^2 (|\hat{h}_{R/B}(\omega_1,\omega_2)|^2 + |\hat{h}_{R/B}(\omega_2,\omega_2)|^2)$
  - $e^L$  is not stationary and not white

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 $\rightarrow$  The basis L,  $\mathbf{C}^{G/M}$ ,  $\mathbf{C}^{R/B}$  is appropriate to address the problem

# **MMSE chrominance filters**

- → The chrominance should be denoised <u>before</u> estimating the luminance
  - Wiener-like FIR chrominance filters of size  $N \times N$ optimal for a learning image base: linear systems of size  $N^2 \times N^2$  to solve:

$$\mathbf{A}_{G/M}\mathbf{h}_{G/M} = \mathbf{b}_{G/M}$$
$$\mathbf{A}_{R/B}\mathbf{h}_{R/B} = \mathbf{b}_{R/B}$$

[Dubois, IEEE ICIP, 2006]

In presence of noise:

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$$(\mathbf{A}_{G/M} + \frac{8}{3}\sigma^{2}\mathbf{I})\mathbf{h}_{G/M} = \mathbf{b}_{G/M}$$
 [Condat, *IEEE ICIP*, 2010]  
$$(\mathbf{A}_{R/B} + 4\sigma^{2}\mathbf{I})\mathbf{h}_{R/B} = \mathbf{b}_{R/B}$$



#### Results $\sigma = 20$



#### **Results** $\sigma = 20$



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#### Results

#### **Original Image**



# $\sigma = 20$ **Results** Hirakawa *et al., IEEE TIP,* 2006



### Results

#### Zhang et al., IEEE TIP, 2007



# gipsa-lab $\sigma = 20$

#### Results

#### Zhang et al., IEEE TIP, 2009









 We can show that demosaicking by frequency selection solves the following variational problem:

minimize **d**  $\mu \|\nabla d^L\|_{\ell_2}^2 + \|\nabla d^{G/M}\|_{\ell_2}^2 + \|\nabla d^{R/B}\|_{\ell_2}^2$  s.t.  $d^{X[\mathbf{k}]} = v[\mathbf{k}], \ \forall \mathbf{k}$ 

- Key point: the chrominance energy is more penalized:  $\mu \approx 0.05$
- Remark 1: the solution does not depend on the choice of the chrominance basis.
- Remark 2: this generic approach can be used with every CFA.

• New denoisaicking strategy:

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• step 1) solve  
minimize 
$$_{\mathbf{d}} \| \mathbf{d} \|_{\mathrm{TV}} := \mu \left\| \sqrt{(\nabla_x d^L)^2 + (\nabla_y d^L)^2} \right\|_{\ell_1} + \left\| \sqrt{(\nabla_x d^{G/M})^2 + (\nabla_x d^{R/B})^2 + (\nabla_y d^{G/M})^2 + (\nabla_y d^{R/B})^2} \right\|_{\ell_1}$$
  
s.t.  $d^{X[\mathbf{k}]} = v[\mathbf{k}], \ \forall \mathbf{k}$ 

• step 2) denoise  $d^L$ 

### Primal-dual optimization algorithm

[Chambolle and Pock, 2011, "A first-order primal-dual algorithm for convex problems with applications to imaging"]

• Choose  $\alpha > 0$ , set  $\beta = 1/(8\alpha)$ ,  $\mathbf{b} = (0)$ 

Iterate

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$$\forall X \in \{R, G, B\}, \ \mathbf{b}_{(n+1)}^{X} = \mathbf{b}_{(n)}^{X} + \alpha \nabla \bar{d}_{(n)}^{X}$$

$$\forall \mathbf{k} \in \mathbb{Z}^{2}, \ \mathbf{b}_{(n+1)}^{L}[\mathbf{k}] = \frac{\mathbf{b}_{(n+1)}^{L}[\mathbf{k}]}{\max(1, |\mathbf{b}_{(n+1)}^{L}[\mathbf{k}]|/\mu)} \frac{\mathbf{b}_{(n+1)}^{X}[\mathbf{k}]}{\max(1, \sqrt{|\mathbf{b}_{(n+1)}^{G/M}[\mathbf{k}]|^{2} + |\mathbf{b}_{(n+1)}^{R/B}[\mathbf{k}]|^{2})}$$

$$\forall \mathbf{k} \in \mathbb{Z}^{2}, \ \forall X \in \{R, G, B\}, \ d_{(n+1)}^{X} = d_{(n)}^{X} + \beta \operatorname{div} \mathbf{b}_{(n+1)}^{X}$$

$$\forall \mathbf{k} \in \mathbb{Z}^{2}, \ d_{(n+1)}^{X[\mathbf{k}]}[\mathbf{k}] = v[\mathbf{k}]$$

$$\overline{\mathbf{d}}_{(n+1)} = 2\mathbf{d}_{(n+1)} - \mathbf{d}_{(n)}$$

#### Method by frequency selection



Result



#### Result

#### Method by TV minimization



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### Choice of the CFA: a packing problem

• Fourier interpretation of mosaicking:

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$$\hat{v}(\boldsymbol{\omega}) = \sum_{X \in \{L, C_1, C_2\}} \widehat{u^X}(\boldsymbol{\omega}) * \widehat{\operatorname{cfa}^X}(\boldsymbol{\omega}), \quad \boldsymbol{\omega} \in \mathbb{R}^2$$

→ Idea of Hirakawa [IEEE TIP, 2008] to design the CFA directly in Fourier domain

- Iuminance in the baseband
- chrominance far away from the luminance

# Choice of a R,G,B CFA

• Periodic patterns: the Bayer CFA is optimal

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→ can we do better with aperiodic CFAs? [Condat, IVC, IEEE ICIP]

$$\hat{v}(\boldsymbol{\omega}) = \frac{1}{\sqrt{3}} \widehat{u^L}(\boldsymbol{\omega}) + \sum_{C \in \{C_1, C_2\}} \widehat{u^C}(\boldsymbol{\omega}) * \widehat{\operatorname{cfa}^C}(\boldsymbol{\omega}), \quad \boldsymbol{\omega} \in \mathbb{R}^2$$



# Generic variational demosaicking

minimize  $\mathbf{d} \ \mu \| \nabla d^L \|_{\ell_2}^2 + \| \nabla d^{G/M} \|_{\ell_2}^2 + \| \nabla d^{R/B} \|_{\ell_2}^2 \qquad s.t. \ d^{X[\mathbf{k}]} = v[\mathbf{k}], \ \forall \mathbf{k}$ 

- Quadratic problem → linear system to solve
- Iterative method (Jacobi)

[Condat, IEEE ICIP, 2009]



Bayer

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random CFA, type I

random CFA, type II





- 6 couleurs [1,<sup>1</sup>/<sub>2</sub>,0], [0,<sup>1</sup>/<sub>2</sub>,1], [<sup>1</sup>/<sub>2</sub>,0,1], [<sup>1</sup>/<sub>2</sub>,1,0], [0,1,<sup>1</sup>/<sub>2</sub>], [1,0,<sup>1</sup>/<sub>2</sub>]
- Color isotropy: two chrominance channels modulated in quadrature at the same frequency
- Designed to maximize  $\gamma^C$ ,  $\gamma^L$

$$\rightarrow \quad \omega_0 = \frac{2\pi}{3}$$

cfa<sup>*R/B*</sup>[**k**] = 
$$\gamma^{C}(-1)^{k_1}\sqrt{2}\sin(\omega_0 k_2 - \varphi)$$
  
cfa<sup>*V/M*</sup>[**k**] =  $\gamma^{C}(-1)^{k_1}\sqrt{2}\cos(\omega_0 k_2 - \varphi)$ 

 $cfa^{L}[\mathbf{k}] - \gamma^{L}$ 









Condat





### Conclusion

- Demosaicking by frequency selection
  - linear (simple, stable), fast, efficient
  - noisy case: just demosaick and denoise the luminance
  - variational interpretation: generic, extension to non-quadratic penalty
- Can be inserted in a realistic reconstruction pipeline using variance stabilization
- There are better alternatives to the Bayer CFA (more robust to aliasing and noise)
  - R,G,B aperiodic CFAs
  - 2x3 periodic CFA

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